AUTOFOCUS ALGORITHMS PERFORMANCE EVALUATIONS USING AN INTEGRATED SAR PRODUCT SIMULATOR AND PROCESSOR

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Abstract—The design and development of synthetic aperture radar (SAR) system for a particular application often requires redesign of software and hardware to optimize the system performance. In addition, evaluations of the performance of existing autofocus and image formation algorithms are required for the SAR system designers to select a most suitable algorithm for a given image quality requirements. This is a time-consuming taskwithout a reconfigurable and comprehensive software package. Thus, a comprehensive SAR integrated simulator and processor software is needed to aid the system designers in optimizing all the system parameters and performance. This paper presents an integrated SAR simulator and processor (iSARSIMP) software package and the performance of three selected SAR autofocus algorithms has been evaluated as examples to demonstrate the usefulness of the iSARSIMP for SAR system designers. In the performance evaluation, simulated and actual SAR raw data were used for further analysis and comparison of the three selected autofocus algorithms.

1. INTRODUCTION

Both satellite and airborne SAR data are subject to a number of perturbations which lead to unknown phase changes in the raw data. The effect of these phase changes or errors is that the SAR imagery will be defocused (blurred) in the azimuth (cross-range) dimension. Autofocus algorithms are computer-automated estimation and compensation techniques of residual phase errors in SAR imagery. Evaluations of the performance of existing autofocus algorithms are required for the SAR system designer for a selection of a most suitable autofocus algorithm for a given image quality requirements. In addition, the design and development of a typical SAR system often requires redesign of software and hardware to optimize the system performance. Thus, a complete SAR integrated simulator and processor software is needed to aid the system designers in optimizing all the system parameters and performance.

This paper introduces an integrated SAR simulator and processor (iSARSIMP) software package, where it is applied to analyze the performance of three selected autofocus algorithms. The iSARSIMP software is implemented by using Matlab^{$\overline{\textcircled{b}}$} application software. A complete simulator would model end-to-end SAR process, including the sensor-target geometry, the antenna and receiver systems, the operation of a signal processor, and the production of a radar image [1, 2]. The developed iSARSIMP is capable to perform mission planning, terrain modelling, autofocus and image processing algorithms evaluations as well as for understanding SAR processes. The iSARSIMP actually is an extension work of earlier developed iSIM simulator package [1]. However, various major enhancements can be found in the iSARSIMP as compared to iSIM. The iSARSIMP is a complete SAR simulator and processor enhanced with three image processing algorithms and various autofocus algorithms. In addition, one-dimensional (1D) and 3-dimensional (3D) SAR images plots also available for image quality analysis. The design of iSARSIMP is based on modular simulation and processing platform, which consists of various independent modules that share a pool of data files. Each module may be developed and executed separately, depending on individual applications.

The data format of iSARSIMP is a simplified version of the CEOS (Committee of Earth Observations Satellites) standard on SAR data set [1, 3]. The SAR data records will use the same data format for all SAR product types [1] in iSARSIMP. By having common formats, users from various working groups would be able to analyze and merge data from multiple resources.

Besides, three established SAR image formation algorithms are implemented in iSARSIMP to process the simulated and actual SAR raw data. The implemented image formation algorithms are Range Doppler algorithm (RDA), Chirp Scaling algorithm (CSA) and Omega-K algorithm (ω KA) [4]. The RDA, CSA and ω KA are the most common precision SAR processing algorithms used for remote sensing data [4]. In addition, comparison study and performance analyses of the three selected autofocus algorithms have been conducted using the developed iSARSIMP. The autofocus algorithms are tested on both simulated complex data and actual SAR raw data from RADARSAT-1.

2. THE ISARSIMP TOOL

The structure of iSARSIMP is a modular-based SAR simulation and processing platform as shown in Figure 1. It consists of various independent modules that share a pool of data files. Each module may be developed and executed separately, depending on individual applications. In order to exchange data resources, the iSARSIMP requires an interpreter to convert their task-specific results to a common format. Figure 2 shows the main interface of the iSARSIMP. Basically it is consists of two main modules: (a) SAR Simulator module and (b) SAR Processor module.

Figure 1. Structure of modular-based iSARSIMP.

2.1. SAR Simulator Module

Figure 2(a) shows a snapshot of the SAR Simulation Module. The SAR simulator module consist of five sub-modules namely (i) SAR

Figure 2. iSARSIMP. (a) SAR simulator module, (b) SAR processor module.

parameters, (ii) Range domain parameters, (iii) Azimuth domain parameters, (iv) SAR data simulation and (v) Radarsat-1 SAR data extraction. The main function of this module is to assist system designers in designing a SAR system. The design parameters in each sub-module can be modified and saved for a new SAR system design. All the other related parameters in sub-modules will be automatically updated when a particular parameter is modified or changed. The SAR data simulation module is able to generate simulated Level-0 raw SAR data, which is saved in the modified CEOS format [1]. Besides, the Radarsat-1 SAR data extraction module function is to extract a particular area of data from Radarsat-1 raw data [4], which can be saved in Matlab[®] mat file format.

2.2. SAR Processor Module

A snapshot of the SAR Processor Module of iSARSIMP software is shown in Figure 2(b). There are three common SAR processing algorithms implemented in this module to process the raw data (level 0) to be SAR image (level 1). The implemented SAR processing algorithms are Range Doppler algorithm (RDA), Chirp Scaling algorithm (CSA) and Omega-K algorithm $(\omega **K**A)$ [4]. In addition, the processed SAR image (level 1) will be displayed on the SAR processor module and can be exported to standard image format such as JPEG. For SAR image quality evaluation and analysis, three focal quality indicators namely (i) 3 dB resolution (3 dBR), (ii) peak sidelobe ratio (PSLR), (iii) signal-to-noise ratio (SNR), (iv) integrated sidelobe ratio (ISLR) and (v) image entropy (IE) of a processed SAR image are provided in this module. Moreover, the inclusion of onedimensional in range and azimuth domain plots, two-dimensional SAR images as well as three-dimensional SAR images plots provide a useful tool for the performance comparison and analysis of various SAR autofocus and image formation algorithms.

3. AUTOFOCUS ALGORITHMS PERFORMANCE EVALUATION USING ISARSIMP

The distance between radar platform and the center of scene being imaged must be known accurately for demodulation of radar returns in a SAR imaging process. When this distance is not measured or known accurately, the SAR data will be corrupted by phase error. The phase error function, $\theta_e(y)$ that varies with each received echo (in azimuth domain) will degrade the SAR image. The perturbed SAR signal after Fourier transform, $S_e(X, Y)$ is given as:

$$
S_e(X,Y) = S(X,Y)e^{j\theta_e(y)}\tag{1}
$$

where X and Y are the range and azimuth spatial frequency variables. The SAR autofocus algorithm is to estimate the phase error, $\theta_e(y)$ and subsequently removes the phase error.

The three selected autofocus algorithms in this performance evaluation using iSARSIMP are phase gradient algorithm (PGA), non-overlapping sub-aperture autofocus (NSA) algorithm and Particle Swarm optimization (PSO) based autofocus [5, 6] algorithm. Various autofocus algorithms have been proposed in the literature over the past 20 years. The most popular and widely utilized is PGA algorithm, which is presented by Eichel et al. in 1989 [7, 8]. PGA determines the phase error by estimates the phase differences between rangecompressed SAR data, and subsequently integrates it. It has been shown that a linear unbiased minimum variance (LUMV) estimate of the gradient of the phase error is given by [7]:

$$
\hat{\theta}_{lumv}(y) = \frac{\sum_{n=1}^{N} \text{Im} \left[\dot{s}_e(y) s_e^*(y) \right]}{\sum_{n=1}^{N} |s_e(y)|^2} = \dot{\theta}_e(y) + \frac{\sum_{n=1}^{N} |s_e(y)|^2 \dot{\theta}_n(y)}{\sum_{n=1}^{N} |s_e(y)|^2}
$$
(2)

where $\dot{\theta}_e$ and \dot{s}_{en} are, respectively, the first derivative of θ_e and s_e ; and the s_e is shifted and windowed SAR image data.

A more recent algorithm is non-overlapping sub-aperture autofocus (NSA), proposed by [9]. In the basic NSA, the azimuth length is divided into K_a smaller sub-apertures. The unwrapped phase gradient of each sub-aperture is independently estimated using a conventional optimization approach. Further, the second derivative of the phase is computed to remove the phase-slope discontinuities at the borders of sub-apertures. The algorithm is innovative because it uses a search technique that does not require the computation of a gradient [9]. However, the authors of the algorithm have made no comparison with other autofocus algorithms in for 2D simulated and real SAR data.

Another innovative algorithm is PSO based autofocus algorithm proposed by [5, 6]. The power-to-spreading noise ratio (PSR) and image entropy (IE) are used as the focal quality indicator to search for optimum solution. PSO is a population-based stochastic optimization technique based on the movement of swarms and inspired by social behaviour of bird flocking or fish schooling [10].

Figure 3. Ideal 2D and 1D SAR images plots of the 3 simulated point targets.

Figure 4. Ideal 3D plot of SAR images of the 3 simulated point targets.

3.1. Example 1: Simulated Data

In order to examine the performance of various autofocus algorithms, the raw data for selected 3 simulated point targets (separated by 500 m in range domain) SAR image need to be generated using SAR Simulator Module. The reflectivity of the 3 simulated point targets is set at 1.0 (max), 0.8 and 0.6 respectively. All others simulation parameters can be found from Figure 2(a). Figure 3 shows the ideal 2D and 1D SAR images plots of the 3 simulated point targets using Range Doppler Algorithm (RDA) from SAR Processor Module. For better visualization, two 3D plots of SAR images of the 3 simulated point targets are shown in Figure 4. In order to evaluate the performance of the selected autofocus algorithms, a most common phase error, namely low-frequency high-order polynomial phase errors (LF-HPE) is introduced in the simulated SAR image.

Figure 5. (a) Simulated SAR image corrupted seventh-order polynomial phase error, (b) Compensated by PGA algorithm, (c) Seventh-order polynomial phase error function (actual phase error), (d) Actual and estimated phase error functions by PGA.

Figure 5(a) shows a defocus image of the 3 simulated point targets corrupted by a seventh-order polynomial phase error. As shown in Figure 5(a), the high-order polynomial phase error mainly defocus the mainlobe regions but only cause minor distortion in the sidelobes regions of the simulated point targets signal. In addition, Figure $5(c)$ shows the plot of the seventh-order polynomial phase error function (actual phase error) used in the test. Figure 5(b) illustrates the compensated SAR image by using PGA algorithm, while the actual and estimated phase error functions are depicted in Figure 5(d). The visual

Figure 6. (a) Simulated SAR image compensated by PSO based algorithm, (b) Compensated by NSA algorithm, (c) Actual and estimated phase error functions by PSO, (d) Actual and estimated phase error functions by NSA.

inspection of Figure $5(b)$ as compared to Figure $5(a)$ shows significant improvement in the image quality. It can be observed from Figure $5(d)$ that the phase errors (LF-HPE) in the image have been successfully estimated and subsequently being minimized after compensated by PGA algorithm.

In addition, Figure $6(a)$ and Figure $6(b)$ show the compensated 2D SAR image by using PSO based and NSA autofocus algorithms respectively. When comparing Figure $6(a)$ and (b) with Figure $5(a)$ by visual inspection, significant image quality improvement can be observed where phase errors almost totally eliminated. From Figures 6(c) and (d), it can be noticed that phase error estimated by PSO based autofocus algorithm is closer to actual phase error as compared to NSA autofocus algorithm.

Figures 7(a), (b), (c) and (d) show the 3D SAR image plots for cases where the 3 simulated point targets are corrupted by high-order polynomial phase error (HPE), compensated by PGA, compensated by PSO based and compensated by NSA algorithms respectively. From Figure 7(a), it can be observed that the amplitude and 3dB resolution (in azimuth domain) of the corrupted image are degraded as compared to the ideal simulated image in Figure 4. A good restoration from corrupted image can be seen in Figures $7(b)$, (c) and (d) by using PGA, PSO and NSA algorithms respectively.

Figure 7. (a) Corrupted simulated SAR image (3D), (b) Compensated by PGA (3D), (c) Compensated by PSO (3D), (d) Compensated by NSA (3D).

In order to evaluate the quality of two-dimensional SAR image, signal-to-noise ratio (SNR) , $3 dB$ resolution $(3 dBR)$, peak sidelobe ratio (PSLR) and image entropy (IE) are used as focal quality metrics. The 3 dBR is defined as -3 dB mainlobe of a point target response in the azimuth direction. This is the main performance criterion since the minimum space separation of two points that can be distinguished will determine how well the final image is focused. The PSLR is the ratio between the height of the largest sidelobe and the height of the mainlobe [4]. The PSLR should be kept small to avoid small targets masked by adjacent strong targets. The PLSR is analyzed in one dimension (in azimuth domain) after range and azimuth compression. On the other hand, image entropy is a conventional focal quality indicator used to measure how well an image is focused. As an image becomes blurred or corrupted by phase errors, the IE of the image will increase. Thus, an image is best focused when the value of IE of the image is minimum. An approximation of the IE is given in [5, 11], for SAR data in discrete form as:

$$
IE = -\sum_{m=0}^{M-1} \sum_{n=0}^{N-1} s_{m,n} \ln s_{m,n}
$$
 (3)

where $s_{m,n}$ is the normalized target reflectivity of an image.

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Table 1 shows the results of the SNR, 3 dBR, PSLR (1D azimuth domain) and IE of the simulated SAR image for the ideal, corrupted by LF-HPE and post-compensation by the selected autofocus algorithms. From Table 1, it is found that PGA algorithm recorded the highest SNR, lowest PSLR and IE value follows by PSO and NSA algorithms. It should be noted that the smaller value of IE indicates better focus of the image. All the selected autofocus algorithms manage to improve the 3 dBR from $4\,\mathrm{m}$ (corrupted) to $1\,\mathrm{m}$. The results in Table 1 indicate that PGA recorded the best performance among the three algorithms, follows by PSO and NSA. However, the differences in performance among the three algorithms are rather small. In term of the computational time, NSA is the fastest algorithm while PSO based algorithm recorded the longest time.

	SNR (dB)	3 dBR(m)	$PSLR$ (dB)	ΙE
Ideal SAR Image	6.7383		-21.9957	0.154105
Corrupted by LF-HPE (7-order polynomial)	6.5258	4	-11.2174	0.261200
PGA compensation	6.7965		-22.0156	0.154704
PSO based autofocus compensation	6.7697		-20.5156	0.158882
NSA compensation	6.7352		-20.1328	0.170616

Table 1. SNR, 3 dBR and IE of the simulated 2D SAR image.

3.2. Example 2: Actual SAR Data

In order to quantitatively compare the performance of PGA, PSO based autofocus and NSA algorithms, a selected set of actual SAR raw data [4, 5] extracted from an existing space-borne SAR sensor (RADARSAT-1) is employed in this test. The image entropy is used again as a measure of the image quality for the 2D SAR image. However, the SNR is not used in this test as the *signal* and *noise* is no longer clear in the case of natural terrains of actual SAR image. RADARSAT-1 is Canada's first commercial Earth observation satellite and was launched in 1995. It uses a SAR sensor to image the Earth at a single frequency of 5.3 GHz and its data are stored in Committee of Earth Observations Satellites (CEOS) format. For this test, only a selected portion (a port of Vancouver area, Canada) of RADARSAT-1 SAR raw data is employed.

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Figure 8. (a) Original actual SAR image from RADARSAT-1 data, (b) Corrupted image.

Figure 9. (a) Compensated by PGA, (b) Compensated by PSO.

Figure 8(a) shows a processed SAR image of the selected portion of the RADARSAT-1 raw data using RDA image formation algorithm, while a corrupted version of Figure $8(a)$ by the LF-HPE is depicted

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in Figure 8(b). As illustrated in Figure 8(b), the LF-HPE blurs the image and consequently degrades the resolution of the image. The degree of distortion depends on the number of order and value of the coefficients of the polynomial phase error. In addition, Figures 9(a) and 9(b) show the compensated SAR image which was corrupted by LF-HPE by using PGA and PSO based autofocus algorithms respectively. The visual inspection of Figures $9(a)$ and $9(b)$ as compared to Figure 8(b) shows that great improvement in the image focus quality after reconstructions of the PGA and PSO based autofocus algorithms. Lastly, the compensated SAR image by NSA algorithm as depicted in Figure 10 also shows significant improvement in the image focus quality as compared to Figure 8(b). However, from Figures 8–10, it can be observed that PGA and PSO algorithms exhibit higher performance as compared to NSA algorithm in the actual SAR image phase errors elimination.

Figure 10. Compensated by NSA.

In order to qualitatively compare the performance of PGA, PSO based autofocus and NSA algorithms, the results of the IE of the processed images as shown in Table 2 will be used as the focal quality metric. From Table 2, it can be found that smaller value of IE (indicate better focus) is obtained for the SAR images after compensated by PGA, PSO and NSA autofocus algorithms. In addition, it is also found that PGA and PSO algorithms recorded lower IE values as compared to NSA algorithm. The results of IE indicate that PGA achieves the

Table 2. IE of the actual SAR image.

best performance in phase error elimination follows by PSO algorithms. However, the NSA algorithm recorded the shortest computational time in phase error estimation while PSO algorithm requires the longest computational time.

4. CONCLUSION

The performance of the three selected SAR autofocus algorithms have been analyzed and compared using an integrated SAR simulator and processor (iSARSIMP) software package. Other than autofocus algorithms performance analysis, the iSARSIMP is also integrated with three popular SAR image formation algorithms (RDA, CSA and ω KA), SAR raw data generator, simulator, output viewer in 1D, 2D and 3D plots options. The developed iSARSIMP is a comprehensive software tool for design, optimize, analyze, simulate and process SAR related product. Thus, it can assist system designers and researchers to evaluate SAR system design, processing techniques, autofocus algorithms and so on for a given SAR system and image quality requirements. The simulated and actual SAR data testing results further validate the potential of NSA and PSO based autofocus algorithms in estimating SAR phase errors with comparable performance with the well-established PGA algorithm.

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